

**A NOTE ON REVISIONS IN ARIMA-BASED  
SIGNAL EXTRACTION**

Agustín Maravall

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Abstract

Revisions for different admissible decompositions in ARIMA-based Signal Extraction are analysed. It is seen how the canonical decomposition maximizes the variance of the revision in the preliminary estimate of the signal. As shown in an example, the result may extend to more general decompositions.

Keywords: ARIMA models; Signal Extraction; Revisions; Canonical Decomposition.



## 1. Background

Let  $z_t$  be the outcome of the ARIMA process:

$$\phi(B) z_t = \theta(B) a_t , \quad (1.1)$$

and we wish to decompose  $z_t$  into:

$$z_t = p_t + u_t , \quad (1.2)$$

where  $p_t$  is the signal and  $u_t$  the noise. The signal follows the process (with the same AR polynomial):

$$\phi(B) p_t = \alpha(B) b_t$$

where  $b_t$  and  $u_t$  are mutually independent white-noises. The MA polynomial  $\alpha(B)$  and the variances  $\sigma_b^2$  and  $\sigma_u^2$ , are determined from the system of equations which results from equating the covariances in both sides of the identity:

$$\theta(B) a_t = \alpha(B) b_t + \phi(B) u_t \quad (1.3)$$

It is well-known that, in general, if a solution exists, it will not be unique. Of all the admissible decompositions, the one that has a maximum noise variance is termed "canonical". Its use has been recommended in the work of Box, Bell, Burman, Hillmer, Pierce and Tiao, among others (see, for example, the references in Bell-Hillmer, 1984.) The model for the canonical signal is non-invertible, and an important property of the canonical decomposition is the following (see Hillmer-Tiao, 1982):

Let  $p_t^*$ ,  $u_t^*$  be the canonical components.  
 Any other admissible decomposition  $(p_t, u_t)$  satisfies:

$$p_t = p_t^* + e_t \quad (1.4)$$

where  $e_t$  is white-noise, orthogonal to  $p_t^*$ .

Since the components are solely defined in terms of their statistical properties, there seems to be no point in removing noise from the noise component and adding it to the signal. Thus the canonical decomposition is a sensible choice. The purpose of this note is to look at one property of the canonical decomposition which is of applied interest.

Let  $\psi(B) = \theta(B)/\phi(B)$  and  $\psi_p(B) = \alpha(B)/\phi(B)$ .  
 Conditional on  $[z_t, -\infty < t < \infty]$ , the optimal estimate of  $p_t$  is given by:

$$\hat{p}_t = k_p \frac{\psi_p(B) \psi_p(F)}{\psi(B) \psi(F)} z_t = v(B) z_t, \quad (1.5)$$

where  $k_p = \sigma_b^2 / \sigma_a^2$  and  $F = B^{-1}$ . The filter  $v(B)$  is symmetric, centered in  $t$ , and may extend from  $-\infty$  to  $+\infty$ . At time  $t$ , since observations are available up to and including  $z_t$ , the "end" part of the filter ( $v_{t+1} z_{t+1} + v_{t+2} z_{t+2} + \dots$ ) cannot be applied. As shown in Cleveland-Tiao (1976), an optimal procedure is to replace unknown future observations with their conditional expectations at  $t$ . As time goes by, forecasts are either updated or replaced by new observations, which induces revisions in the estimate of  $p_t$ . Some properties of these revisions have been analysed by Pierce (1980). Write the final estimate as:

$$\hat{p}_t = v_0 z_t + \sum v_j (z_{t-j} + z_{t+j}) .$$

where (for the rest of the paper) the summation signs extend from  $j=1$  to  $j=\infty$ . The concurrent estimate will be given by:

$$\hat{p}_t^0 = v_0 z_t + \sum v_j (z_{t-j} + \hat{z}_t(j)) .$$

so that the revision is:

$$d_t = \hat{p}_t - \hat{p}_t^0 = \sum v_j e_t(j) . \quad (1.6)$$

where  $e_t(j) = z_{t+j} - \hat{z}_t(j)$ . Hence the revision  $d_t$  is a weighted average of forecast errors. Revisions are of applied interest: since the final estimate is the best estimate, if revisions are large, the preliminary or concurrent estimate (the one used in monitoring and policy making) will be unreliable. In practice, thus, large revisions are (understandably) feared.





## 2. Signal Extraction

Consider first the decomposition of an IMA(1,1) into signal plus noise (see Box-Hillmer-Tiao, 1979). Equation (1.1) becomes:

$$\nabla z_t = (1-\theta B)a_t \quad (2.1)$$

and an admissible component for  $p_t$  is of the form:

$$\nabla p_t = (1-\alpha B)b_t$$

with  $-1 \leq \alpha \leq \theta$  (so that  $\sigma_u^2 \geq 0$ ). The canonical decomposition implies  $\alpha = -1$  (hence the pseudospectrum of  $p_t$  has a zero for  $\omega = \pi$ .)

For any admissible decomposition, it is easily seen that:

$$v(B) = k_p \frac{(1-\alpha B)(1-\alpha F)}{(1-\theta B)(1-\theta F)}$$

and, since (1.3) implies

$$(1-\theta B)(1-\theta F)\sigma_a^2 = (1-\alpha B)(1-\alpha F)\sigma_b^2 + (1-B)(1-F)\sigma_u^2.$$

it can also be expressed as:

$$v(B) = 1-k \frac{(1-B)(1-F)}{(1-\theta B)(1-\theta F)}.$$

where  $k = \sigma_u^2 / \sigma_a^2$ . Let  $H_0 = 2/(1+\theta)$  and  $H_1 = (\theta-1)/(1+\theta)$ ; the weights of  $v(B)$  are found to be:

$$v_0 = 1-k H_0 ; v_j = -k \theta^{j-1} H_1 \quad (j \geq 1).$$

thus, in (1.6),

$$d_t = -k H_1 \Sigma \theta^{j-1} e_t(j) .$$

Since, for (2.1),

$$e_t(j) = a_{t+j} + (1-\theta) \Sigma_{i=1}^{j-1} a_{t+i} .$$

it is finally found:

$$d_t = -k(1-\theta) \Sigma \theta^{j-1} a_{t+j} .$$

or, letting  $k_0 = -k(1-\theta)$ ,

$$d_t = k_0 y_t .$$

where  $y_t$  is the AR(1) process:

$$(1-\theta F)y_t = a_{t+1} .$$

Thus, except for a scale factor, the series of revision errors is the same for all admissible decompositions. Also, considering that, after simplifying, it is obtained that

$$\text{Var} (d_t) = \frac{\sigma_u^4}{\sigma_a^2} \frac{1-\theta}{1+\theta} .$$

since  $\sigma_a^2$  and  $\theta$  are the same for all admissible decomposition, the maximum revision variance is obtained when the noise variance is maximized. Thus the canonical decomposition maximizes the variance of the revision.

This result generalizes to any signal plus noise decomposition of an ARIMA model. Let the ARIMA model be (1.1), and we wish to decompose  $z_t$  as in (1.2), with  $u_t$  white-noise. Since:

$$\psi(B) \psi(F) \sigma_a^2 = \psi_p(B) \psi_p(F) \sigma_b^2 + \sigma_u^2,$$

the filter  $v(B)$  in (1.5) is equal to:

$$v(B) = 1-k \frac{\phi(B) \phi(F)}{\theta(B) \theta(F)}$$

Hence, from (1.6),

$$d_t = -k \sum \zeta_j e_t(j),$$

where  $\zeta(B) = \psi(B)^{-1}$ , and the coefficients  $\zeta_j$  are fixed, once the overall model is known. Since the same is true for  $e_t(j)$  and  $\sigma_a^2$ ,

$$\text{Var}(d_t) = \sigma_u^4 M,$$

where  $M$  is the same for all admissible decompositions. Therefore, in the general signal plus noise decomposition the canonical solution maximizes the variance of the revision. (Notice that, again, the revision error series is the same for all admissible decomposition, aside from a scale factor.)



### 3. The Case of More than Two Components

The previous result may extend to the case of more than two components. As an example, consider the simplest ARIMA model which accepts a non-trivial trend/seasonal/irregular decomposition (see Pierce-Maravall, 1984):

$$\nabla_2 z_t = a_t . \quad (3.1)$$

The admissible components are given by:

$$\left. \begin{aligned} (1-B) p_t &= (1-\alpha B) b_t \\ (1+B) s_t &= (1-\beta B) c_t \\ u_t &\sim \text{white noise.} \end{aligned} \right\}$$

with

$$\begin{aligned} \sigma_b^2 &= \sigma_a^2 / 4(1-\alpha)^2 \\ \sigma_c^2 &= \sigma_a^2 / 4(1+\beta)^2 \\ \sigma_u^2 &= \sigma_a^2 [-\alpha/4(1+\alpha)^2 + \beta/4(1+\beta)^2] . \end{aligned}$$

Since it has to be that  $\sigma_u^2 \geq 0$ , the admissible parameter region has to satisfy:

$$\alpha(1+\beta)^2 - \beta(1-\alpha)^2 \leq 0 .$$

and is represented in Figure 1. (It can be seen that, always,  $\alpha \leq 3-2\sqrt{2}$ ,  $\beta \geq -(3-2\sqrt{2})$ .) The canonical components imply  $\alpha = -1$  and  $\beta = 1$ , so that the pseudospectra of  $p_t$  and  $s_t$  have a zero for  $\omega = \pi$  and  $\omega = 0$  respectively (Figure 2).

The estimate of  $p_t$  is found to be.

$$\hat{p}_t = \frac{1}{4(1-\alpha)^2} [2(1-\alpha+\alpha^2)z_t + (1-\alpha)^2(z_{t-1}+z_{t+1}) - \alpha(z_{t-2}+z_{t+2})] .$$

The concurrent estimate  $\hat{p}_t^0$  will be obtained by replacing  $z_{t+1}$  and  $z_{t+2}$  by  $\hat{z}_t(1)$  and  $\hat{z}_t(2)$  in the above expression. Since for (3.1),  $e_t(1) = a_{t+1}$  and  $e_t(2) = a_{t+2}$ , after simplifying:

$$d_t = \hat{p}_t - \hat{p}_t^0 = \frac{1}{4} [a_{t+1} - \frac{\alpha}{(1-\alpha)^2} a_{t+2}] .$$

$$\text{Var} (d_t) = \frac{\sigma_a^2}{16} [1 + \frac{\alpha^2}{(1-\alpha)^4}]$$

Again, for  $-1 \leq \alpha \leq 3-2\sqrt{2}$  (the admissible region for  $\alpha$ ), the variance of  $d_t$  is maximized for  $\alpha = -1$ , in which case:

$$\text{Var} (d_t) = \frac{\sigma_a^2}{16} [1 + \frac{1}{16}]$$

(see Figure 3). If  $\delta_t$  denotes the revision in the concurrent estimate of  $s_t$ ,  $\delta_t = \hat{s}_t - \hat{s}_t^0$ , then it is straightforward to verify that

$$\delta_t = \frac{\sigma_a^2}{16} [-a_{t+1} + \frac{\beta}{(1+\beta)^2} a_{t+2}] .$$

hence

$$\text{Var } (\delta_t) = \frac{\sigma_a^2}{16} \left[ 1 + \frac{\beta^2}{(1+\beta)^4} \right] ,$$

which, for the admissible region  $(-3+2\sqrt{2} \leq \beta \leq 1)$ , reaches a maximum for  $\beta = 1$ . The canonical components, therefore, maximize the variance of the revisions in the concurrent estimates of  $p_t$  and  $s_t$  (and hence, of the concurrently seasonally adjusted series.)





#### 4. Summary and Conclusion

We have seen that, for ARIMA-based signal extraction, the canonical decomposition (which maximizes the variance of the noise) implies maximum revision variances. Since any admissible component is equal to the canonical one plus orthogonal white-noise, the result states that the cleaner the component, the larger the revision of its estimate. It may sound puzzling that the smoother a signal, the larger the revision. However, it is obvious that the estimate of the signal which minimizes the revision is  $\hat{p}_t = z_t$ , when no noise is extracted and the signal is noisiest.

Although this maximum revision property of the canonical decomposition is somewhat inconvenient, it does not make sense to reduce revisions by improperly labelling as signal, what is purely white-noise variation.

Figure . 1

Admissible Parameter Region

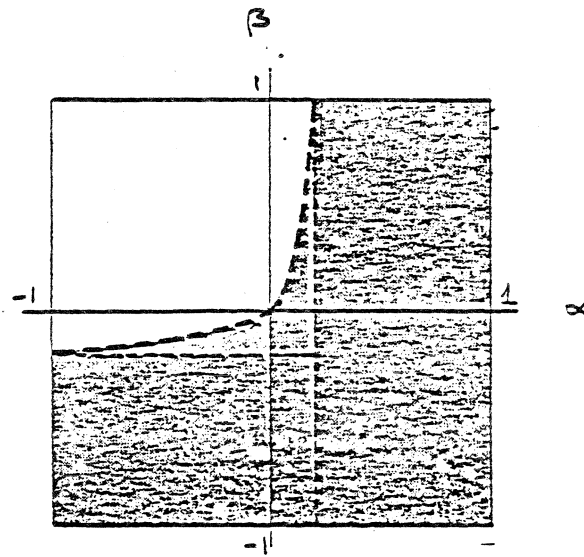


Figure 2

Canonical Decomposition of  $\nabla_2 z_t = a_t$

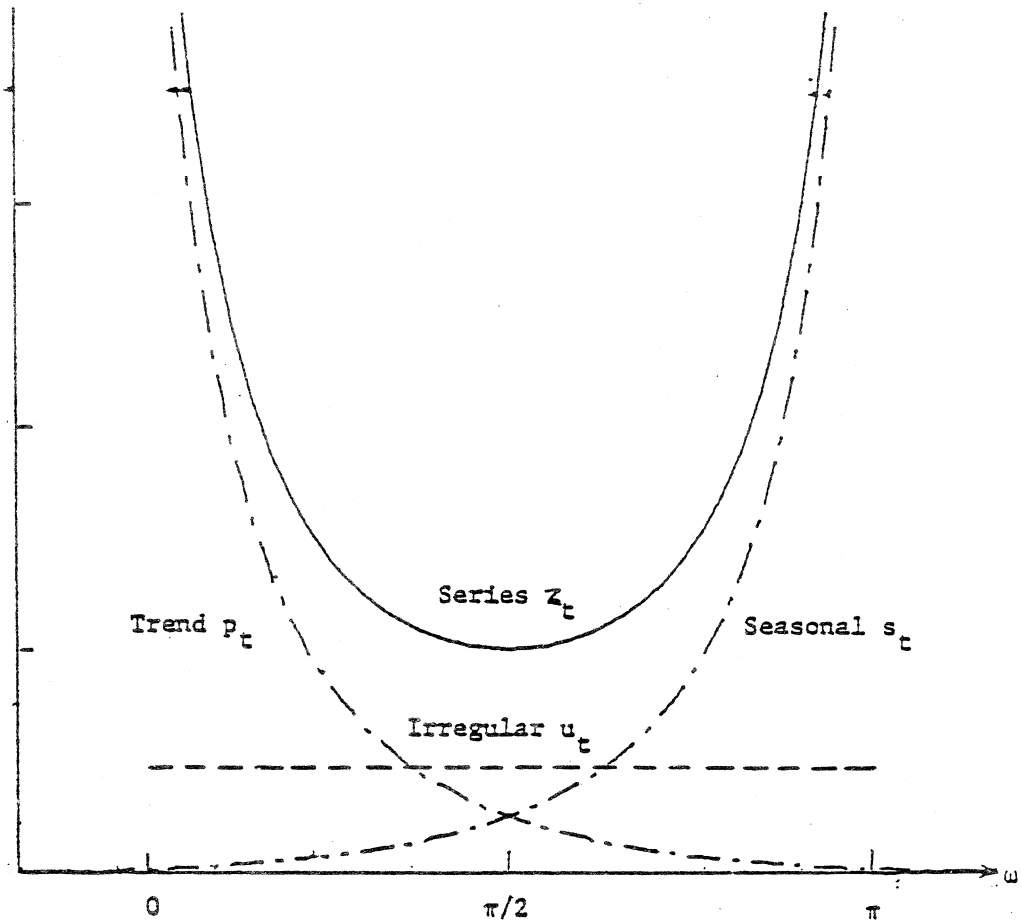
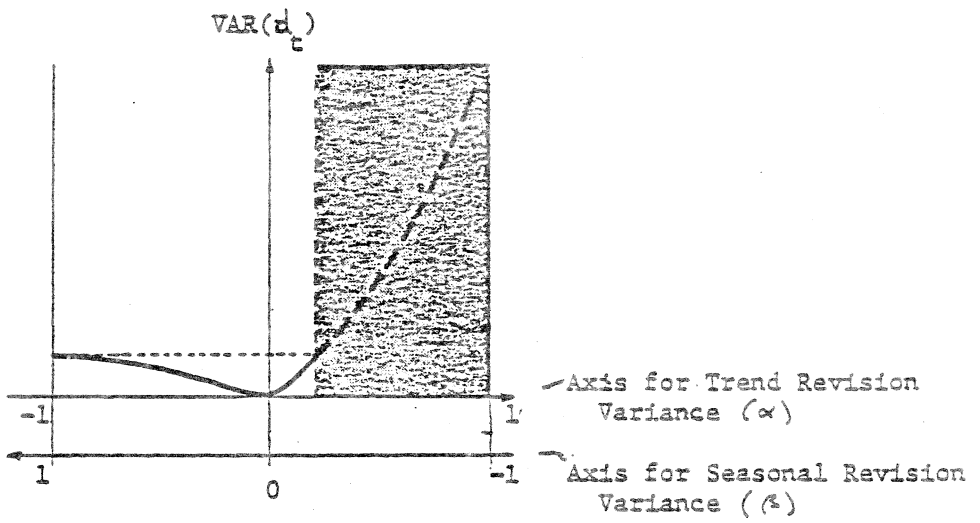


Figure 3

Variance of Revisions in  
Concurrent Estimates



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